

## Today's Agenda

- Real-Time Systems Overview

## Real-Time Systems Overview

- Introduction
- Examples of Real-Time Systems
- Characteristics of Real-Time Systems
- Summary

## What is it?

- Any system in which the time at which output is produced is significant
  - From Oxford Dictionary of Computing
- Any system that is required to react to externally generated input stimuli within a finite and specified period

The correctness of a real-time system depends on the logical results PLUS the time of delivery.

## Timing Requirements

- Often expressed as **deadlines**, i.e., time when execution must be completed.
  - Can be specified as a point in time or a delta-time interval
- **Hard deadline**: Late delivery may result in serious consequences
- **Firm deadline**: Late delivery is no good, but does not put you in trouble
- **Soft deadline**: Late delivery is undesirable, but may be good results (within some upper limit)

## Concurrency

- Most of real-time systems are **concurrent**
  - Multiple threads are often created to handle external events from different sources
  - Many events need to be processed in parallel
- **Communication** and **synchronization** are the two **cores** issues in a concurrent system
  - Communication is concerned with how different threads exchange information with each other
  - Synchronization is concerned with how to enforce a certain order among concurrent events

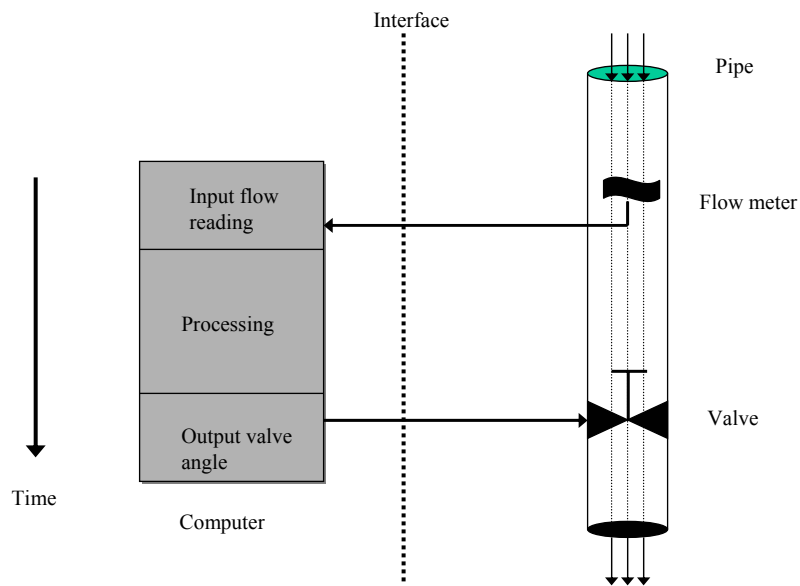
## Misconceptions

- Real-time systems are **concurrent** systems
  - Concurrent systems do not have explicit time
- Real-time systems are **real fast** systems
  - A real-fast system may not always satisfy its timing requirements
- Hardware **over-capacity** is enough
  - Without appropriate resource management, there is no appropriate resource distribution

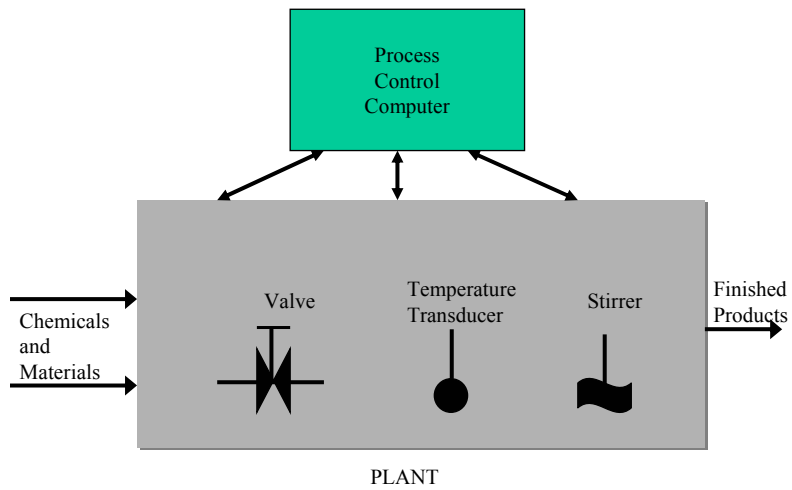
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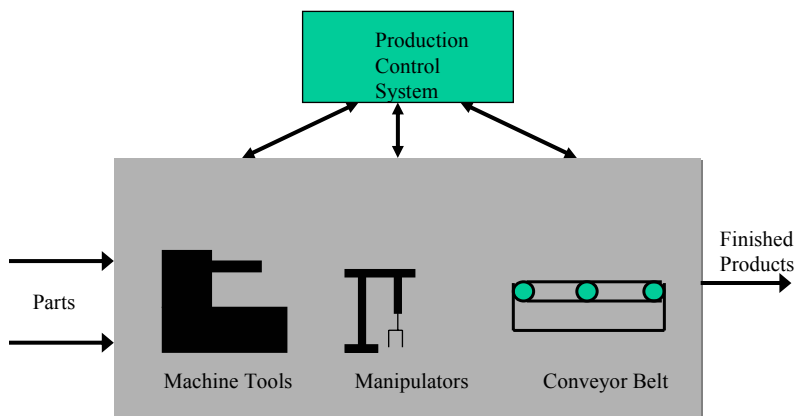
## A Fluid Control System



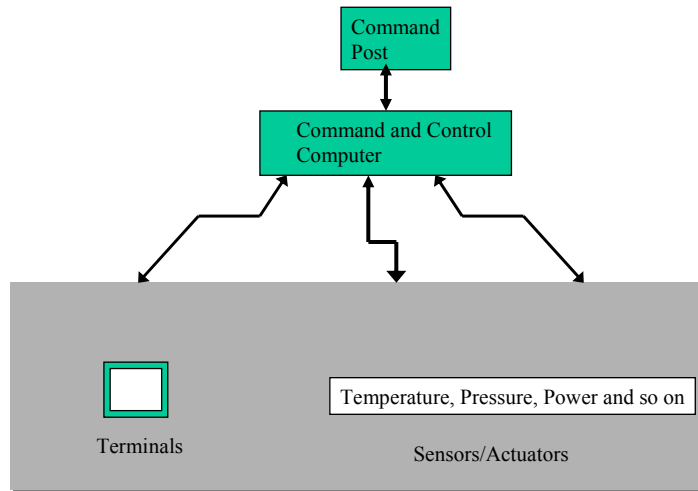
## A Process Control System



## A Production Control System



## A Command And Control System



## More Examples

- ❑ Cars: engine control, ABS, drive-by-wire
- ❑ Planes: stability, jet engine, fly-by-wire
- ❑ Military: weapons, command and control
- ❑ Domestic: microwave, thermostat, dishwasher,
- ❑ Medical: pacemaker, medical monitoring
- ❑ Protection: intruder alarm, gas/smoke detection

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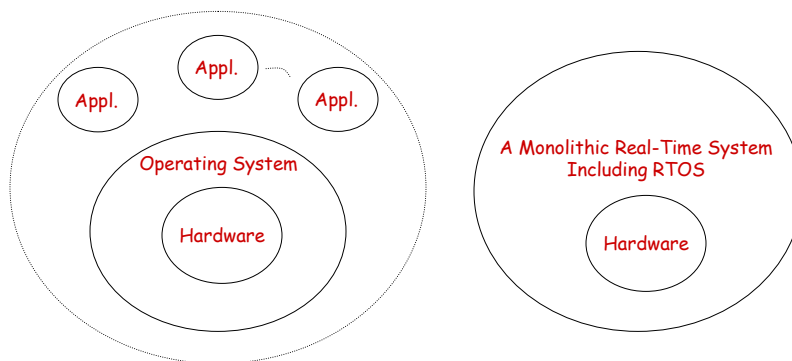
## Common Characteristics (1)

- **Embedded system:** a component of a larger engineering system.
  - Many people consider embedded systems is synonymous real-time systems.
- **Concurrent system:** the system simultaneously controls and/or reacts to different aspects of the environment, many events that need to be processed in parallel.
- **Safety critical system:** not only reliable but also safe, if it fails then without causing injury or loss of life. The development of safe system involves architectural redundancy.
- **Reactive system:** there is a continuous interaction with the environment, event-driven and must respond to external stimuli, system response is typically state dependent.

## Common Characteristics (2)

- ❑ Operate under more severe constraints than "normal" software systems.
  - e.g., Must operate with a minimum memory footprint and with minimum of support hardware.
- ❑ Control and monitor physical processes in a timely fashion
  - Often need to directly interact with various physical devices
- ❑ Perform without direct human intervention, i.e., not interactive
  - Do not provide conventional computer display or keyboard.
- ❑ Perform reliably for long periods
  - Are not supposed to terminate

## RTOS vs. GPOS



## Predictability

- Real-time systems must be **predictable** under certain assumptions about **workload** and sufficient **resource availability**.
- **Static predictability** can be achieved if complete knowledge about workload and resource availability is known at design time.
- The underlying OS must have predictable behavior; otherwise, it is impossible to achieve predictability at the application level

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## Summary

- Real-time systems must produce the right results at the right time.
- Two main challenges in designing and developing real-time systems
  - How to ensure the satisfaction of timing requirements
  - How to deal with concurrency, i.e., thread/process synchronization and communication
- Real-time systems are typically closed
  - No admission of applications whose timing characteristics are not known